

## ICC-4C-500 Industrial Current Controller – 4 Channels



### Main features:

- Graphic user interface *Optotune Cockpit* for control via USB or Ethernet
- Up to 4 Optotune tunable lenses simultaneously (up to +/-500 mA per channel)
- Communication interfaces:
  - USB, UART, I2C, Ethernet with PoE+ capability
  - Analog input (0 – 10V)
  - Trigger OUT
  - Trigger IN
  - 5 x Status LEDs (R/G)
- Software SDKs for Python and C# available
- RoHS, REACH and CE certified

### Mechanical specifications

Dimensions (L x W x H)	164 x 105 x 44	mm
Weight	700	g
USB connector	Micro B, USB2.0	
Max. USB cable length <sup>1</sup>	5	m
Max. lens cable length (Hirose) <sup>2</sup>	10	m
Accepted DC Barrel Plug	2.1 I.D. x 5.5 O.D. x 10.0	mm
Output connector	Hirose HR10G-7R-6SB(73)	
Auxiliary output connector	Standard rectangular header, 100" (2.54mm) pitch	34 pins
I/O connector	Standard rectangular header, 100" (2.54mm) pitch	20 pins
Mounting	T-slots for standard M4 nut	

### Electrical specifications

Supply voltage range	24 to 48	VDC
PoE specification	PoE+ 803.3at	
Total power consumption (max)	25 (with factory presets) 37	W

### Thermal specifications

Operating temperature	0 to 60	°C
Storage temperature	-40 to 85	°C

### Driver outputs

Maximum current (4Ch., simultaneously)	±500	mA
Minimum current step	65	µA
Resolution	14	bits
Front-end voltage <sup>3</sup> (configurable)	6 – 18 (factory default = 12)	V
Output voltage limit	4 – 16	V
Output stage topology	Full bridge, filtered PWM (load not grounded)	
Digital communication with lens	Dedicated I2C bus for each channel, 400kHz max.	
I2C logic level (pullups implemented)	3.3	V
Power for I2C (each channel separately)	3.3	V

<sup>1</sup> Maximum tested cable length in lab conditions, actual performance may depend on electromagnetic environment. Longer lengths are possible using active USB cables.

<sup>2</sup> Maximum tested cable length in lab conditions. Maximum cable length may depend on electromagnetic environment.

<sup>3</sup> The front-end voltage supplies the output stage. The output voltage is slightly lower than the front-end voltage.

Power for logics, max. current	4 x typ. 100 (each channel over current protected)	mA
Status LED (main + each channel)	Red, Green, Orange LED	

### Driver inputs

Analog inputs level (4 channels)	0 – 10	V
Analog input resolution (each channel)	16	Bits
Analog input BW	10	kHz
Digital inputs	4xGPIO, I2C, UART, SYNC_A, SYNC_B, MCU RESET	
Digital inputs logic level	3.3 ( <b>NOT</b> 5 V tolerant)	V

### Standard products

ICC-4C-500	ICC-4C-500 Controller only
ICC-4C-500 Extension Kit	Extension kit containing: <ul style="list-style-type: none"> <li>• Adaptor board for lenses (with 30 cm extension cable)</li> <li>• Micro-USB cable</li> <li>• DIN Rail clamp Kit</li> </ul>
ICC-4C Power Adapter	Power adapter (EU, CH, US, UK, CN main cables available)

### Mechanical layout

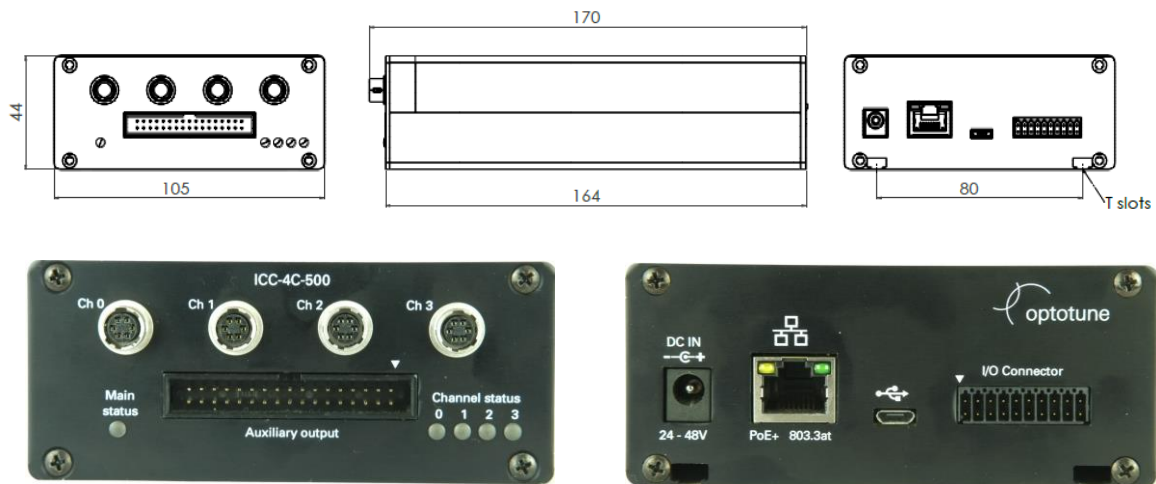


Figure 1: Mechanical dimensions, front and back panel details of the ICC-4C-500.

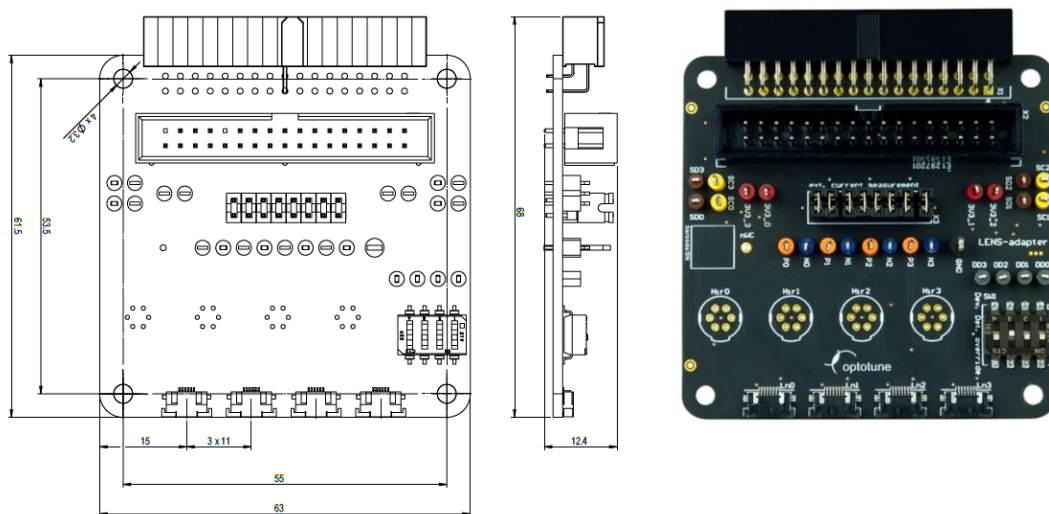


Figure 2: Mechanical dimension of adapter board (optional accessory).

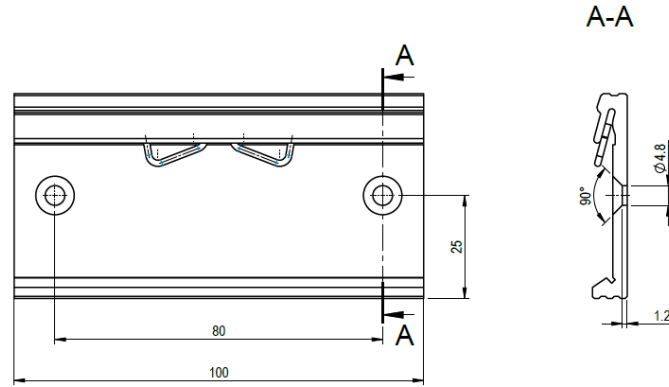


Figure 3: DIN Rail adapter (optional accessory).

### Input/Output connector pinout

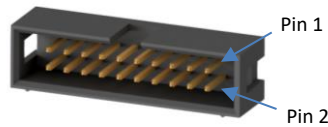


Figure 4: Connector<sup>4</sup>: Würth Electronics header 100 mil 90deg.

Pin	Signal	Value	Function
1	AnalogIn2	0..10 V	Analog input signal #2
2	AnalogIn3	0..10 V	Analog input signal #3
3	AnalogIn0	0..10 V	Analog input signal #0
4	AnalogIn1	0..10 V	Analog input signal #1
5	nRESET	0..3.3V (CMOS level)	Driver reset signal (inverted level)
6	AGND	-	Analog signal ground
7	USART_EXT_TX	0..3.3V (CMOS level)	UART transmit line
8	SYNC_B	0..3.3V (CMOS level)	Synchronization input B
9	USART_EXT_RX	0..3.3V (CMOS level)	UART receive line
10	SYNC_A	0..3.3V (CMOS level)	Synchronization input A
11	GND	-	Digital ground
12	GPIO3_SPI_MOSI	0..3.3V (CMOS level)	General purpose digital IO #3 or SPI MOSI signal (Trigger OUT/IN)
13	I2C_HOST_SDA	0..3.3V (CMOS level)	I2C data line from host
14	GPIO2_SPI_MISO	0..3.3V (CMOS level)	General purpose digital IO #2 or SPI MISO signal (Trigger OUT/IN)
15	I2C_HOST_SCL	0..3.3V (CMOS level)	I2C clock line from host
16	GPIO1_SPI_NSS	0..3.3V (CMOS level)	General purpose digital IO #1 or SPI SlaveSelect signal (Trigger OUT/IN)
17	GND	-	Digital ground
18	GPIO0_SPI_SCK	0..3.3V (CMOS level)	General purpose digital IO #0 or SCK signal (Trigger OUT/IN)
19	VCC_EXT_IN	24...48 V	External DC supply voltage positive input
20	GND_EXT_IN	-	External DC supply voltage negative input

<sup>4</sup> First samples of the ICC-4C might have a different connector. Please contact us if the connector doesn't look like in the figure above.

## Lens connectors pinout



FPC Molex connector		Hirose connector	
Pin	Function	Pin	Function
1	I2C GND	1	Lens (+ pole)
2	Lens (- pole)	2	Lens (- pole)
3	Lens (+ pole)	3	I2C GND
4	I2C SDA	4	I2C Vcc 3.3V
5	I2C SCL	5	I2C SCL
6	I2C Vcc 3.3V	6	I2C SDA

Figure 5: Lens connectors pinout.

## Connecting the adapter board

The adapter board can be connected directly to Auxiliary Output connector (below the Hirose connectors) or with the dedicated extension cable (Figure 6).



Figure 6: Adapter board connection options.

## Connecting to a lens with industrial (Hirose) connector

The connection of lenses with industrial connector (Hirose) is straightforward. Simply connect the cable to the plug until a “click” sound is heard, the position of the pins is unambiguous. Hot plugging of the Hirose connector is safe.

## Connecting to a lens with FPC cable

The flex cable can be plugged directly into the Molex connector of the adapter board (Figure 7). Open the connector clamp with tweezers, then insert the flex cable fully with the copper pads facing upwards. Close the black clamp.

**IMPORTANT: Do NOT hot plug the flex cable from the adaptor board, it might damage the controller!**

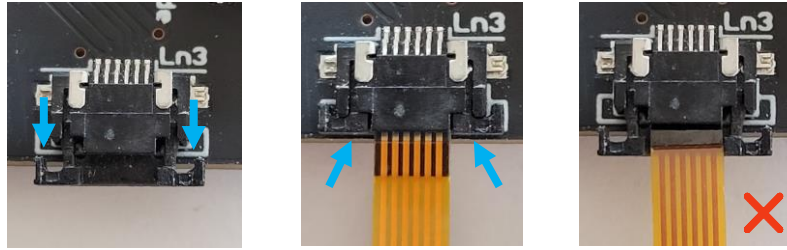


Figure 7: Proper connection to a lens with flex cable and wrong connection example with flipped flex cable and not enclosed connector.

## ICC-4C-500 Main status and Channel status LEDs

LED	Color	Legend
Main Status	Red	Power on, no connection
	Orange	Operation OK (possible error)
	Green	Operation OK
Channel Status	Red	Device error
	Green	Device detected; operation OK

## Input/Output signals

### Output trigger

The signal generator of the ICC-4C outputs a trigger signal from the GPIOx pins (0,1,2,3 depending on the channel, see **Input/Output connector pinout** for pin assignment).

The trigger signal is HIGH (3.3V, max. 5 mA) at phase 0° of the selected waveform and goes LOW in the middle of the period (Figure 8). For pulse pattern, it reflects the duty cycle.

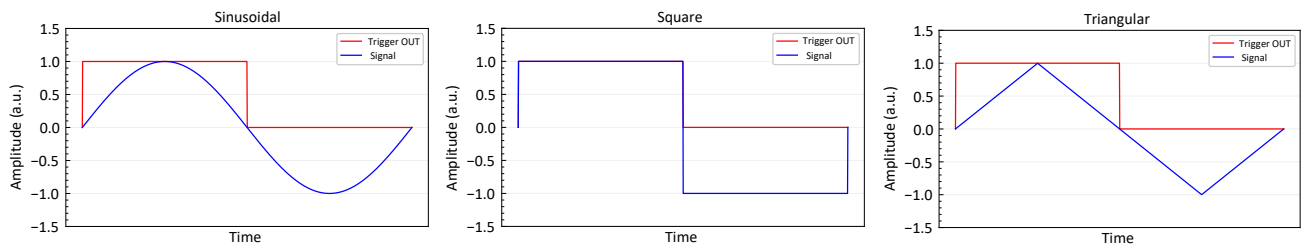


Figure 8: Different waveforms overlapped with the corresponding Trigger OUT signal.

### Input trigger

The signal generator of the ICC-4C can be synchronized with an external input trigger. When the trigger input signal goes HIGH (max 3.3V), the selected waveform starts off at phase 0° (Figure 9). There are two options (see **Input/Output connector pinout** for pin assignment):

- SYNC\_A pin: an input signal to this pin synchronizes all channels simultaneously.
- GPIOx: by default, GPIOx pins are programmed to be used as trigger output (see previous paragraph). They can be reprogrammed to be used as trigger input for single channels (0, 1, 2, 3). In this case, trigger input function is overridden by GPIOx and hence any signal on SYNC\_A is ignored.

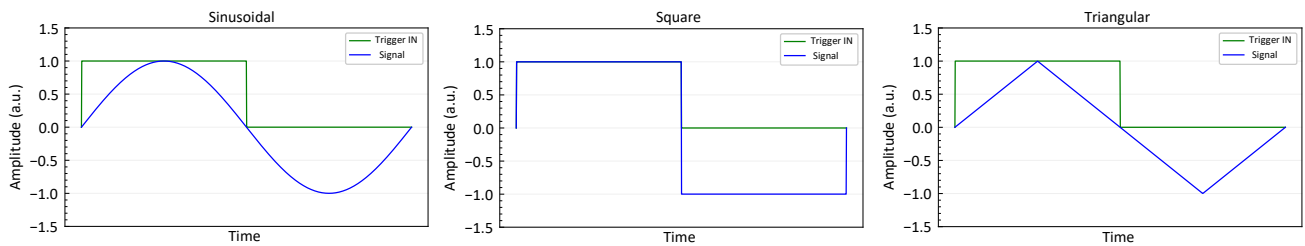


Figure 9: Different waveforms overlapped with an exemplary Trigger IN signal.

### Analog Input

Each individual channel of the ICC-4C-500 can be controlled via a dedicated 0-10 V analog input (see **Input/Output connector pinout** for pin assignment). The resolution of the ADC is 16 bits. The analog input can be mapped to Current or Focal power (if applicable) of the connected lens on the corresponding channel. Both linear and non-linear mapping are possible.

For additional information on how to set up the analog mapping, please refer to the Optotune Cockpit software manual.

### Simple mode communication

Simple mode communication is RS-232 based serial communication interface that can be used to communicate to the device via a Serial Terminal (e.g., *Termite*, *Putty*. Baud rate: 256000, Parity: N, Stop bits: 1, Data bits: 8) or via *Telnet Client* (on Windows OS), if Ethernet communication is used. It employs a set of ASCII characters commands and answers to interact with ICC-4C driver features. Commands and replies are terminated by character sequence CR, LF (resp. 0x0D, 0x0A). The protocol is not case sensitive and white spaces are ignored.

List of simple mode replies:

Simple communication mode reply	Description
OK[CR][LF]	Command accepted and performed without limits.
NO[CR][LF]	Command not accepted, for any reason.
OL[CR][LF]	Command not accepted, because parameter reached lower limit.
OU[CR][LF]	Command not accepted, because parameter reached upper limit.
ERROR[CR][LF]	Command not available.

List of simple mode commands:

Simple mode command	Description
START[CR][LF]	Driver answers "OK" if driver is ready to use and device is detected. Otherwise "ERROR" is received.
STATUS[CR][LF]	Driver answers with status encoded within 4Bytes information. Example: "0x00015000[CR][LF]" See next section for further description of the status bytes.
RESET[CR][LF]	Restarts driver's firmware. Note: no answer is sent via serial line.
GOTODFU[CR][LF]	Starts driver's loader for firmware update. Note: no answer is sent via serial line.
GOPRO[CR][LF]	Starts binary protocol-based mode of serial communication. Serial message CRC is not checked.
GOPROCRC[CR][LF]	Starts binary protocol-based mode of serial communication. Serial message CRC is checked.
GETID[CR][LF]	Answers with firmware serial number. Example: "14352500-00-A[CR][LF]"
GETVERSION[CR][LF]	Answers with firmware version number. Example: "1.0.740706[CR][LF]"
GETGITSHA1	Answers with 40 bytes hexadecimal GIT build identification. Example : "eb8115e6b04814f0c37146bbe3dbc35f3e8992e0[CR][LF]"
GETSN[CR][LF]	Answers with board and device serial number. Example: "Board: CDAA0057, Device: ANAA1234[CR][LF]"

GETDEVICESN[CR][LF]	Answers with serial number of a device connected depending on active channel. Example: "Device: ANAA1234[CR][LF]"
DETECTDEVICE[CR][LF]	Runs device autodetection on active channel. When detection is successful, answers with device name. Example: "XPR[CR][LF]"
SETCHANNEL=%int[CR][LF]	Set active channel. Channel index of ICC-4C is 0-3. Command is used as predecessor of other commands applying on active channel of ICC-4C driver.
GETCHANNEL[CR][LF]	Get active channel returns an integral number of active/selected channel, 0-3 for ICC-4C driver. Example: "2[CR][LF]"
SETCURRENT=%float[CR][LF]	Set current value for active channel. Command supports decimal parameter value in mA units. Current value is limited either by power capabilities of ICC driver itself or connected device.
GETCURRENT[CR][LF]	Answers with value of active channel current setpoint. Returned value is decimal number in units of milliamperes. Example: "15.6[CR][LF]"
SETFP=%float[CR][LF]	Sets focal power of active channel. Command supports decimal parameter value in units of diopters. Focal power is limited to detected lens device capability.
GETFP[CR][LF]	Answers with focal power of lens on active channel. Returned focal power is a decimal number in diopters. If no lens is detected, it returns "NO".
GETFPMIN[CR][LF]	Answers with focal power lower limit of lens device connected to active channel. Returned focal power is decimal value in diopters. If no lens is detected, it returns "NO".
GETFPMAX[CR][LF]	Answers with focal power upper limit of lens device connected to active channel. Returned focal power is a decimal value in diopters. If no lens is detected, it returns "NO".
GETTEMP[CR][LF]	Answers with actual temperature of device connected to active channel. Returned temperature is a decimal value in units of degree Celsius. Example : "27.54[CR][LF]"
SETTEMLIM=%f[CR][LF]	Set operational temperature limit for selected channel in degree Celsius.

### Driver status (refers to "STATUS" command)

The driver "error status" is a 32 bits information about driver itself or a device connected to a certain channel.

The "error status" might have active state, when error status is present or inactive, when error status was present, but currently is inactive.

Byte	Status bit	Driver status
0.	0.	Fault on channel 0 – active
	1.	Fault on channel 0 – inactive
	2.	Fault on channel 1 – active
	3.	Fault on channel 1 – inactive
	4.	Fault on channel 2 – active
	5.	Fault on channel 2 – inactive
	6.	Fault on channel 3 – active
1.	7.	Fault on channel 3 – inactive
	0.	Driver overheat status – active
	1.	Driver overheat status – inactive
	2.	Channel 0: device not detected – active
	3.	Channel 0: device not detected – inactive
	4.	Channel 1: device not detected – active
	5.	Channel 1: device not detected – inactive
2.	6.	Channel 2: device not detected – active
	7.	Channel 2: device not detected – inactive
	0.	Channel 3: device not detected – active
	1.	Channel 3: device not detected – inactive
	2.	Channel 0: Device supply 3.3V power overcurrent – active
	3.	Channel 0: Device supply 3.3V power overcurrent – inactive
	4.	Channel 1: Device supply 3.3V power overcurrent – active
5.	Channel 1: Device supply 3.3V power overcurrent – inactive	
	6.	Channel 2: Device supply 3.3V power overcurrent – active

	7.	Channel 2: Device supply 3.3V power overcurrent – inactive
3.	0.	Channel 3: Device supply 3.3V power overcurrent – active
	1.	Channel 3: Device supply 3.3V power overcurrent – inactive
	2.	I2C communication error – active
	3.	I2C communication error – inactive
	4.	EEPROM reading error -active
	5.	EEPROM reading error – inactive
	6.	Hall sensor out of range – active
	7.	Hall sensor out of range - inactive

### Pro mode communication protocol

Pro Mode communication protocol with additional functionalities is available on request.

### Safety and compliance

The product fulfills the RoHS, REACH and CE compliance standards. The customer is solely responsible for complying with all relevant safety regulations for integration and operation.

For more information on optical, mechanical, and electrical parameters, please contact [sales@optotune.com](mailto:sales@optotune.com)

### Supporting documentation (available on request)

The following support documentation is available on request:

- How to connect ICC-4C to a PC via direct Ethernet connection
- How to configure ICC-4C for Analog Input Mode with Optotune Cockpit and Python